



Engineering and Physical Sciences Research Council



# Electric Fleets with On-site Renewable Energy Sources (EFORES): Data-driven Dynamic Dispatching and Charging under Uncertainties

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**On-site Renewable Energy Source (ORES)** 

This project is to investigate the possibility to intelligently integrate the dynamic charging demand of fleets of electric vehicles with the highly variable On-site Renewable Energy Sources (ORES) by developing a data-driven reinforcement learning (RL) decision support tool.

### The Novelty, Originality and Significance:

Empirical data driven intelligent optimal dispatching and charging schedule of business electric fleets to maximize the efficient use of high variable on-site renewable energy at  $y_{k-12}$  lowest cost of facility investment, and thus more green energy is used in road transport with less impacts on power grid.

## **Problem Description**

The main charging facility at the depot has various ORES (PV, wind generators, etc), a static battery energy storage system (BESS) and a set of EV chargers (either AC or DC). They are connected to a 400 V local distribution network that is connected to the main grid via a transformer. The Energy Hub unit is a bank of unidirectional or bidirectional inverters that connect the ORES and EV charging stations and controls the energy exchange between the supply side and the demand side. The BESS and PV are connected through a DC bus. The challenge is how to integrate the parts to maximize their efficiency and economy.





The uncertainty of wind power is reflected in the distribution of wind speed. This project uses a neural network to combine historical wind speed data and NWP (Numerical Weather Prediction) to predict the wind speed for the power of next time interval. Use this wind speed and convert it with the parameters of the actual wind turbine on site into wind power. This energy is used as the energy supply for the EV fleet. This is also part of the context in the RL algorithm in this project.  $y_k$  is the historical wind speed data at *k* time interval. Then procedure  $y_{k+1}$  into the wind speed- wind power relationship. The equations shows above are the model of the wind turbine. The right figures are the wind speed and wind power distribution in Newcastle, UK.



#### Figure 3: Wind forecasting and energy conversion[1]

The power generated from the plant modeled in [2] during discrete time interval of the day is shown in Figure. 4. The monthly average solar irradiance and ambient temperature from [2] are presented in Figure. 4. The relationship between the power generation and solar irradiance can be expressed as:

## $p_s(t) = GHI(t) \cdot \eta_g A_s$

where GHI(t) (Global Horizontal Irradiance) is the solar irradiance  $(Wm^{-2})$ ;  $\eta_g$  is the solar PV source efficiency;  $A_s$  is the solar PV source effective surface area  $(m^2)$ ;  $P_s(t)$  is the Pv output power. It can be seen from the formula that there is a linear relationship between the generation of GHI and PV energy. The two graphs on the right side of Figure 4 count the distribution of the GHI index and the corresponding standard deviation in the Newcastle area within a day. According to this data, the uncertainty of solar energy can be reflected to provide the environment for the RL algorithm.

Figure 1:Diagram of the electric fleet depot use case with self-generated renewable energy

## Aims and Objectives:

• A systematic investigation of the spatial-temporal pattern and uncertainties of both EV demand and ORE supply.

• An optimised EV dispatching and charging schedule by developing a Reinforcement Dividing the day into 24 time periods by 1 h, and the charging load pf EVs' demand occurs in each time period as shown in Figure.5 and Figure.6.

• Development of a techno-economic analysis tool to evaluate emission reduction in urban environment.

## Methodology

## Reinforcement Learning for optical decision on charging and dispatching

The system block diagram of reinforcement learning is as follows. The environment is constituted by the uncertainty of renewable energies. The reward is the capacity status of the battery. The state function is the actual power and the estimated power. The action consists of charging and non-charging actions of each EV in the fleet.



Figure 4:Daily and monthly distribution of solar energy

## **Electric Vehicle Fleet Demand Modelling**



Figure 5: Hourly power consumption of Leicester [3]

Figure 6:Averaged hourly power load at different month [3]

Future work and Conclusion



Figure 2:Diagram of the reinforcement learning **Project information:** One year project with Scottish Power (Future Networks) and Newcastle City Council

#### The following is a summary of the contents of this poster.

• To maximise economy and efficiency, the RL algorithm is designed to match the uncertain renewable energy supply with the uncertain energy demand of the EFs.

• Based on historical data from Newcastle, create a neural network and a time series algorithm to predict wind speed, then use the expected wind speed to build a model to convert it into uncertain wind power.

• Create an energy demand model for the EV fleet based on the charging and discharging rules.

#### Future work

• A techno-economic-environmental optimisation approach to analysing of emission reduction with collaborative EFs

• Prototyping and case study of a local council.

#### Reference

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[3] D. Xuewu, K. Richard, P. Ghanim, W. Yue, D. Ridoy, B. Edward, M. Mousa, and d. H. Jorden, van. Final report - oslo operational pilot. Technical report, Interreg North Sea Region SEEV4-City, Oslo City Council: Sture Portvik, July 2020.